

**One-stop Robotic Solution for Safe Collaboration** 



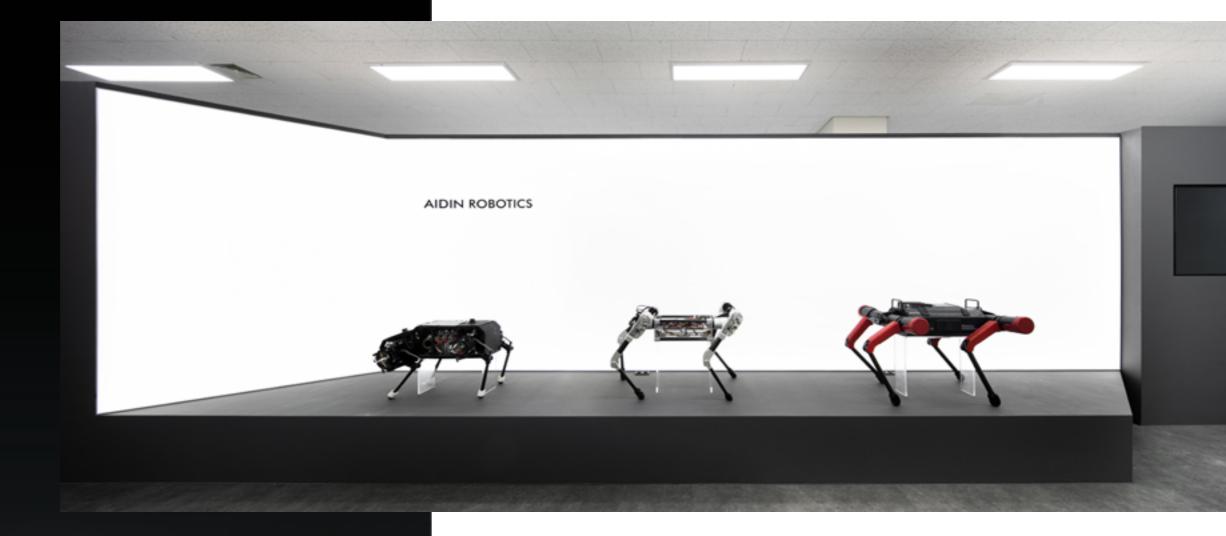
## **AIDIN**

ROBOTICS Inc. is a robot company that <u>started from</u>
Robotics Innovation Laboratory in the Department of Mechanical Engineering at Sungkyunkwan University in South Korea.
Our expertise lies in developing robotic system and Al-driven sensor technologies based on our Field Sensing technology, which we have been accumulating since 1995.

The world's leading field sensing technology



# AIDIN ROBOTICS



"

We are dedicated to the continuous pursuit of our vision: creating a safer working environment and coexistence between humans and robots.

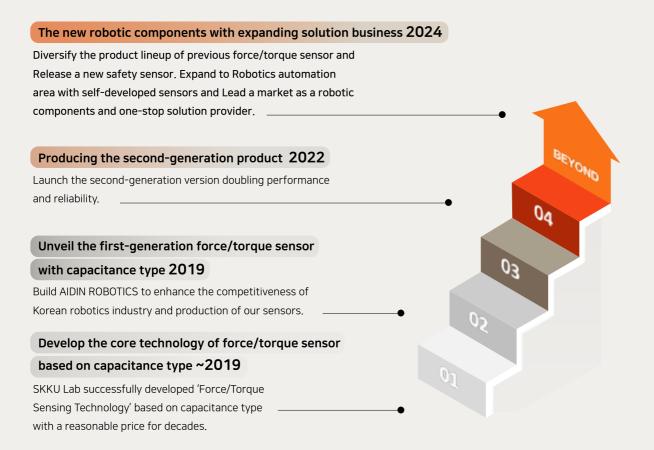
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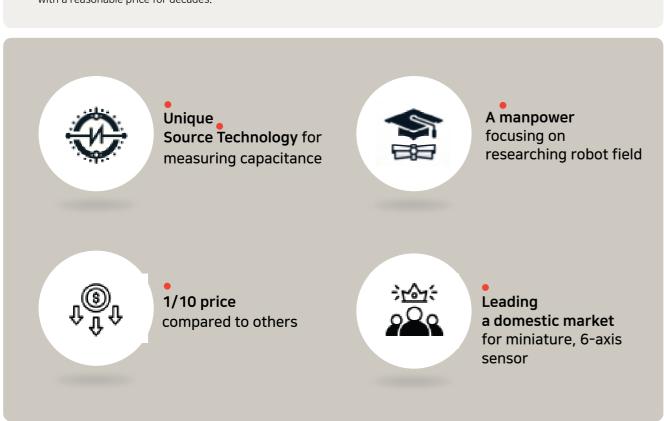
# **One - stop Robotic Solution for Safe Collaboration**

Our focus is on preventing accidents and improving productivity between humans and industrial/collaborative robots.

# The Competitiveness of AIDIN ROBOTICS

The newest Power Sensing Technology which successfully overcomes the limitation of existing force/torque sensing based on capacitance.





### **HISTORY**

2019

Established corporation

2020

Selected as the excellent company of robotics company foundation support program in Gyeong-gi do  $\,$ 

Established Laboratory in company

Selected as The beginning foundation support package program

Certification of Venture Business & Technology with a limit under two billion

Investment attraction from Future Play, Korea Development Bank Capital, Shinhan Bank capital

Selected as Tech Incubator Program for Startup

Award of R-biz Challenge from Korea Association of Robot Industry

Award of Korea Robot Company of The Year 2020

Award of Excellent Product in ROBOTWORLD 2020

2021

Selected as Core-Tech Development Business in Robotics field (Task Scale 3 billion)

Award of Korea Robot Company of The Year 2021 (Two years in a row)

Award of Excellent Product in ROBOTWORLD 2021 (Two years in a row)

2022

Attraction of investment Series A (4.5 billion Scale)

Selected as Managing department developing the customized torque sensor for service robot

MOU Contract for the extension of AI technology corporation for quadruped robot with Snuailab

Award of Korea Robot Company of The Year 2022 (Three years in a row)

Award of Excellent Product in ROBOTWORLD 2022 (Three years in a row)

2023

Selected as Deeptech Incubator for startup 1000+

Participate in ICRA 2023 exhibition

Contract for developing quadruped robot with  $\ensuremath{\mathsf{POSC0}}$ 

Award in International Robot Contest & R-biz Challenge 2023

Award of Korea Robot Company of The Year 2023 (Four years in a row)  $\,$ 

Award of Excellent Product in ROBOTWORLD 2023 (Four years in a row)

Certification of Quality Management System ISO9001:2015

2024

Selected as Cooperation Development Group of the evaluation

focused on operating a skilled robot and supporting gripping performance

(With Korea Electronics Technology Institute, National Institute of Standards and Technology)

Contract for a local supply and sales with DINGS in China

Attracted KRW 15 billion in Series B funding

Signed an MOU with CJ Logistics for the development of robotic picking solution for logistics automation

# Business Area

### Robot Sensor

Our self-developed Force/Torque sensor could be adapted at various industrial robots and grippers. It provides controlling force, measuring torque, and detecting collision. In addition, We help to gauge any distance and contact force with an innovated safety sensor.

#### **Smart Gripper**

It could be combined and utilized following a use environment and manufacturing places with a competitive feature of parallel gripping mode, high-accuracy and high-speed.

#### **Robotics Automation**

Our self-developed technology of gripper, Al vision Algorithm could spread Force control solution for Manufacturing automation applied for delivery process, welding, grinding etc, Robotic picking solution for logistics automation and Quadruped robot solution for inspecting industrial facilities.



### **PRODUCTS**

### Robot Sensor

### Force/Torque Sensor



Smart 6 axis F/T Sensor AFT200-D80



Ultra-thin Joint Torque Sensor

ATSB-Series



Miniature 6 axis F/T Sensor



Safety Sensor

### F/T Sensor KIT



Smart 6-axis F/T Sensor KIT

AFT200-KIT-RB



Smart 6-axis F/T Sensor KIT

AFT200-KIT-NRMK



Panoradar Sensor

ARS-5000

\*Under Development

# Smart Gripper

### **End of Arm Tool**



Smart Gripper
SusGrip
SusGrip-FT

#### **Robot Hand**



AIDIN hand

\*For Research

# \*Robotics Automation System

#### **Robotic Solution**



Force Control Solution for Manufacturing Automation

Co-worker
\*Under Development



Robotic Picking Solution for Logistics

PICKER
\*Released in 2025



Industrial Facility Inspection Soulution
AiDIN

\*Under Development

### **Robot Controller**



Real-time Robot Motion Controller
ARC6

# **Smart 6 axis F/T Sensor**

Model AFT200-D80







### **Dimensions**

80mm x 20.5mm

#### **Applicable Robots**

- Universal Robots
- Doosan Robotics
- Rainbow Robotics, Neuromeka
- Other collaborative/industrial robots



### **Features**

The advanced F/T sensor with high precision based on the fringe effect and capacitance

Essential sensor for robot wrists, enabling tool collision detection, tool weight compensation, force control, direct teaching tool, and object weight measurement

Excellent environmental resistance

4kV discharge test passed

IP56 obtained waterproof/dustproof rating







# **Applications**

Industrial / Collaborative robot

Lead-thru device

Welding, sanding, grinding, assembly operations

Warehouse robot

Smart Factory / Automation

R-R-And-AFT200-D8-C R-R-And-AFT200-D8-EN R-R-Adn-AFT200-D8-EC



Index	Unit	C (CAN)	Value EN (EtherNET)	EC (EtherCAT)
Operating voltage	VDC	5	12	12
Max. safe excitation voltage	VDC	12	24	24
Nominal force range	N		200	
Nominal torque range	Nm		15	
Limit force (Fxyz)	N		300	
Limit torque	Nm		25	
Resolution (Fxyz)	N		0.15	
Resolution (Txyz)	Nm		0.015	
Maximum sample rate	Hz		1,000	
Dimensions	mm		D80 x H20.5	
IP rating		IP56	IP65	IP65
Operating temperature			10-60 °C	

# **Smart 6 axis F/T Sensor KIT**

Model AFT200-KIT-RB AFT200-KIT-NRMK

All-in-One F/T Sensor based on the advanced field sensing technology

#### Applicable Robot

- Rainbow Robotics RB3, RB5, RB10, RB16
- Neuromeka Indy7
- Accepting our partners









### **Features**

- F/T sensor applied with the self-developed technology with capacitance
- Support Plug&Play mode based on collaborative robot brand
- Provide Customized KIT for each collaborative robot band
- Easy Set-up mode in Teaching Pendant

### **Applications**

- Applicable to various processes requiring force control technology
- (Polishing, Sanding, Grinding etc)
- Processes for assembling cables or components
- Industrial robot / Collaborative robot
- Smart Factory / Automation

### **Function**

- Precise force measurement
- Force Control mode that any user could use directly in teaching pendant
- Collision detection and stop function through force measurement

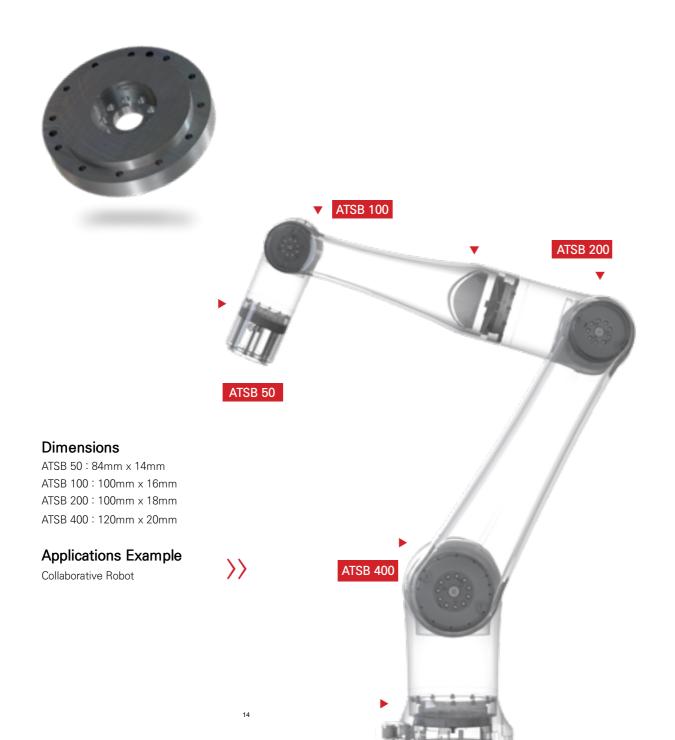
### **Specifications**

Index	Unit	AFT200-KIT-RB C(CAN)	AFT200-KIT-NRMK c(CAN)	
Weight	g	505 (Sensor 236g, Bracket 269g)	635 (Sensor 236g, Bracket 399g)	
Operating voltage	VDC		5	
Max. Safe excitation voltage	VDC		12	
Nominal force range	N	200		
Nominal torque range	Nm	15		
Resolution(Fxyz)	N	0.15		
Resolution(Txyz)	Nm		0.015	
Dimensions	mm	D80 * H52.3 D80 * H56.3		
IP Rating		IP56		
Operating temperature		10-60°C		

# **Ultra-thin Joint Torque Sensor**

Model ATSB 50 / 100 / 200 / 400





### **Features**

Ultra-thin joint torque sensor for collabo-I rative and articulated robots

Ultra-thin joint torque sensor accurately and sensitively measures torque applied to robot joints, enabling precise collision detection and torque control in a compact design.

Excellent environmental resistance 4kV discharge test passed







## **Applications**

Collaborative robot

Wearable robot

Medical device

Rehabilitation robot

Index	Unit	ATSB50	ATSB100	ATSB200	ATSB400
Operating voltage	VDC	5			
Max. safe excitation voltage	VDC		1	0	
Nominal torque range (TN)	Nm	50	100	200	400
Overload (related T <sub>N</sub> )	%	300			
Resolution	Nm	0.03	0.05	0.1	0.2
Weight	g	120	190	210	310
Dimensions	mm	D84 x H14	D100 x H16	D100 x H18	D120 x H20
Sample rate	Hz		1,0	000	
Temperature	10-60 °C				
Interfaces	CAN (2.0 A/B)				
Connector	4 PIN VCC / GND /CAN_H / CAN_L				

# Miniature 6 axis F/T Sensor

Model AFT20-D15 AFT50-D15





**Dimensions** 15mm x 10.5mm

**Application Examples** 

**)**)

Gripper

\* Example Image

# Features

The world's smallest 6-axis force/torque sensor

Suitable for mounting on the gripper's tip end to handle irregular objects such as food, rubber, and plastic injection-molded products without causing damage Applicable to VR, haptic devices, and med-

ical fields as well

Excellent environmental resistance

4kV discharge test passed



KC Registration Number R-R-Adn-AFT20-D15

# **Applications**

Gripper







VR / AR device

vice | Haptic device





3

| Robot hand

| Medical device





Index	Unit	AFT20-D15	AFT50-D15
Operating voltage	VDC		5
Max. safe excitation voltage	VDC	1	10
Force range	N	20	50
Torque range	Nm	0.1	0.25
Break force	N	30	75
Break torque	Nm	0.15	0.35
Force resolution	N	0.2	0.3
Torque resolution	Nm	0.0005	0.001
Sample rate	Hz	10	00
Dimensions	mm D15 x H10.5		
Weight	g 3.2		
Temperature	10-50 ℃		
Interfaces	CAN		
Connector	FPC: 0.5 pitch, 8pin Length: 50, 100, 200 mm For User: CAN_H / CAN_L / VCC / GND		

# **Panoradar Sensor**

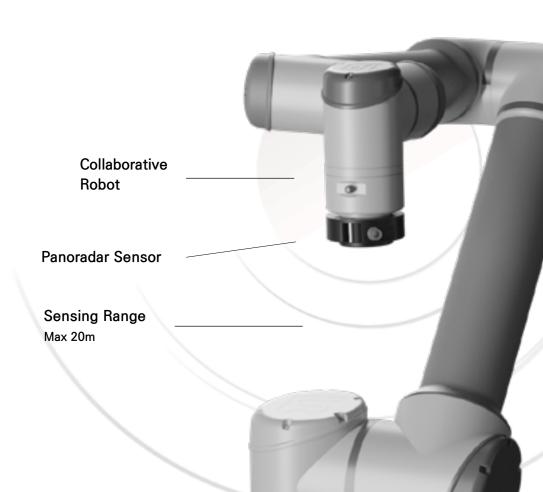
Model ARS-5000

Safety sensor for detecting all people and objects set on a wrist of co-bot without any blind spot

\*Under Development







### **Features**

Safety sensor detecting an surrounding environment and any obstacles to make safe working environment for all workers

Obstacle Detection (Max 20m)

Providing a widen detecting scope and accuracy without any blind spot

(Presence detection / Segmentation / Motion / Tracking / Speed detection)

Range Resolution: 3cm

**▮**360 degree detection FoV

■ Digital output interface (EtherNet)

Obtaining safety zone

### **Applications**

Industrial robot / Collaborative robot

AMR / AGV

Delivery robot

Industrial robot for safety

Quadruped robot

Humanoid robot

	Value	Description
Measurement principle	FMCW – 60GHz	Ultra-wide bandwidth 5.8GHz
	Presence Detection	
Sensing functions	/ Segmentation	
conomy ramous no	/ Motion / Tracking	
	/ Speed Detection	
Measurement	Direction, Proximity and Speed	
Angles	4x (±45°) Azimuth	
Angles	4x (±45°) Elevation FoV	
Working range	Min: 10cm / Max: 20m	Flexible adjustment of aperture angle and distance
Range resolution	Up to 3cm	
Response time	120Hz	Up to 1KHz
Supply voltage	6 – 28Vcc	
Number of detection zones	6 x 4	
Interfaces	EtherNet	RJ45, PoE
Operating temperature	−20 °C +70 °C	
Environment	Harsh environment	Rain / Dust / EMI / Fog
Objects detection	Various objects	Glass, wood, paper, human, metallic objects
Diamondiamo	Diameter: 80mm,	
Dimensions	thickness: 20mm	
Sensor package	All in one	Sensor body + PoE Cable

# **Smart Gripper**

Model SusGrip / SusGrip-FT

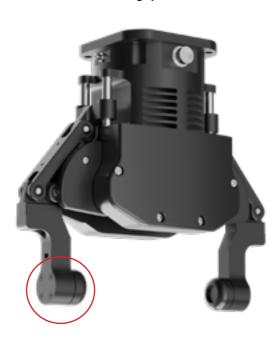
# SusGrip

Robot gripper providing many smart functions based on parallel motion



AFT-Mini Minature 6 axis F/T Sensor

#### Susgrip-FT



Susgrip



### **Features**

A widen parallel motion, High-precision (Max 128mm)

Smart function (Object Detection, Automated Lock)

Precise force control mode with force sensor

(Susgrip-FT model)

High-speed and Strong power with BLDC motor

Safe use (No pinch point)

Intuitive GUI





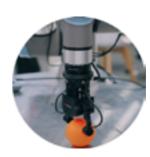
KC Registration Number(SUSGRIP R-R-26a-SusGrip \*Only for SUSGRIP Model

### **Applications**

Various manufacturing process (Pick & Place) / Sorting / Handling / Palletizing / Assembly / Measure

### Industry

Semi-conductor / Service / Logistics / Healthcare / Retail





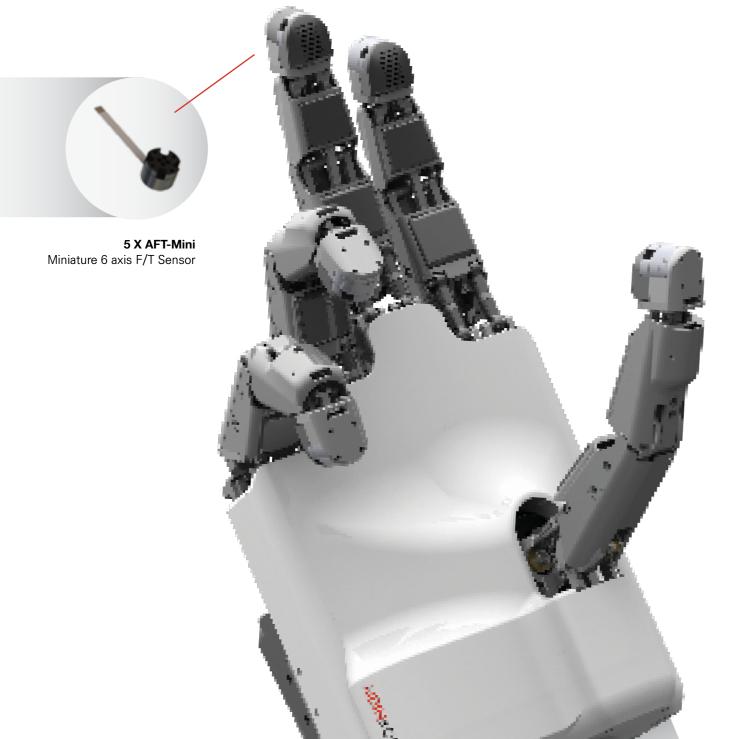
Index	Unit	Value
Gripping force	N	90
Stroke	mm	0-128
Form-fit payload	Kg	5
Voltage	V	24
Max Current	Α	2
Repetition accuracy	mm	0.1
Position resolution	mm	0.2
Speed	mm/s	60
Weight	gram	1215

\*Only for Research Purpose \_\_\_\_\_

# AIDIN HAND

# Human-sized Robot Hand





### **Features**

AIDIN ROBOTICS' proprietary humanoid hand featuring a 6-axis force/torque (F/T) sensor on the fingertip

Dexterous future-proof picking system: Capable of various grasping modes (power, 3-point, pinch, etc.) suitable for different types of objects, and featuring integrated 6-axis F/T sensors, it can reliably handle delicate objects without causing damage

Human-level compact size and light weight

Link-driven mechanism: Offers both high precision and high force efficiency

### **Applications**

Industrial / Collaborative robot

Warehouse picking robot

Home-service robot

Prosthetic hand

Index	Unit	Value
Grasping mode	Mode	Power Mode (cylindrical, spherical, etc.)
Chaoping mode		Precision Mode (pinch, tripod, etc.)
Degree of Freedom (Finger)	DoF	3
Degree of Freedom (Hand)	DoF	15
Finger-tip force	N	20 or 50
Payload	kg	15
Size	mm	291 x 112 x 120
Weight	kg	1.3
Fig. 1. A.	EA	5
Finger-tip sensor	EA	(Miniature 6-axis F/T Sensor, AFT20-D15)

# Real-time Robot Motion Controller

Model ARC6





### **Features**

Real-time motion/force controller for collaborative robots, designed to be compatible with AIDIN ROBOTICS' sensor products

| Equipped with Xenomai, EtherCAT, and ROS middleware

# **Applications**

Industrial / Collaborative robot

Sanding, grinding, welding, assembly applications

Articulated robot control

Warehouse picking robot control

## **Specifications**

Index	Value
CPU	6th Generation Intel Core I Processor
CPU TDP	i7-6600U
Memory Type	DDR4 2133MHz
Power	9 - 36 VDC
Ethernet	Intel i210/i211, 10/100/1000Base-TX
Connection	DP X1, DVI-I X 1, USB 3.0 X 4, USB 2.0 X 2,
	COM ports (RS232, 422, 485)
Operating Humidity	0 - 90 %
Operating temperature	0 - 60 °C
Interfaces	EtherNET, EtherCAT
Operating System	RT-OS (Linux, Ubuntu, Xenomai)

# **Solution**

\*Under developement

# Force Control Solution for Manufacturing Automation

Smart Force/Torque Sensor-Based No-Code Automation Solution

- Immediate task automation through intuitive robot teaching
- Applicable to various tasks such as grinding, polishing, welding, and more







2 X AFT200 Minature 6 axis F/T Sensor (AFT200)











Active surface force control technology through target force setting

Adaptable to various objects, including flat/curved surfaces, narrow areas, and more









controlled to the desired position by the user

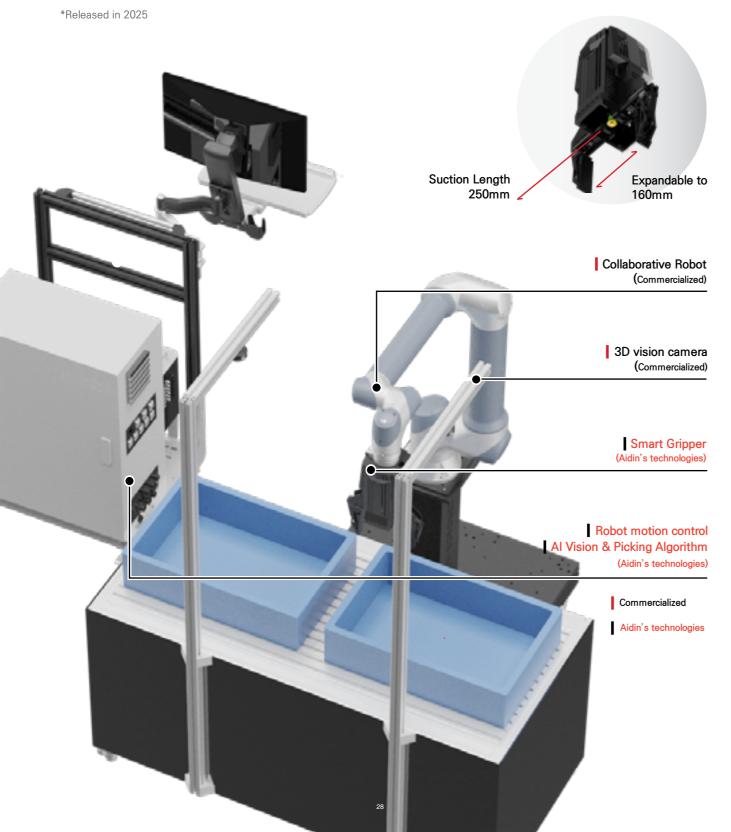
# **Solution**





# Robotic Picking Solution for Logistics

- <u>Effortless Object Recognition and Grasping</u>: Our cutting-edge logistics robot picking system is designed to recognize and grasp random objects without the need for any pre-registration process.
- Integrated Al Vision Technology: We've developed our own Al vision algorithm, seamlessly integrated with a smart gripper capable of handling objects of various types and sizes. This integration allows our system to adapt to all objects found in logistics environments.
- Optimized Object Handling: Through the unified control of both suction and the gripper, our system employs suitable grasping strategies to effectively handle objects, ensuring a seamless and efficient logistics operation.



#### **Productivity**

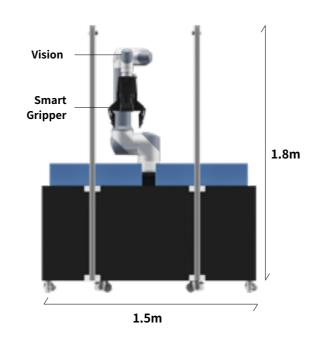
Productivity: 950 pieces per hour
Weight of graspable objects: 5kg
Size of graspable objects: 160mm

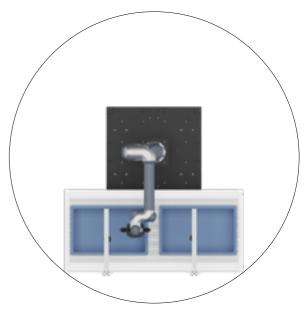
#### **Installation Requirements**

Power: 100-240V, 40-60Hz, 2200W

Compressed Air: 4hp+ compressor recommended

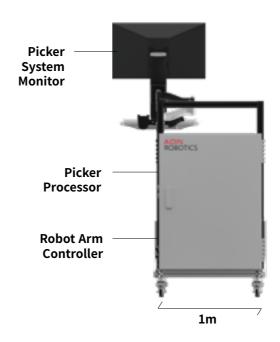
### **System Dimensions**

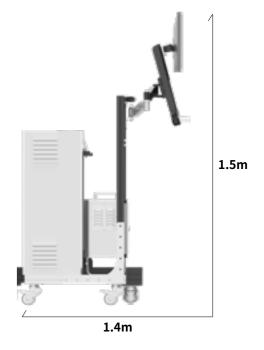




Radius: 1.3m Robot Arm: RB10

### **Picker Controller**





# **Solution**





# Quadruped Robot for Industrial Facility Inspection Solution

\*Under Developent



## **Applications**

Inspecting Hazardous Facilities



| Monitoring Construction Sites



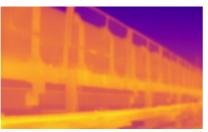
| Smart city Security



| Military / Police / Firefighting



Thermal Inspection



Construction and BIM



### **Features**

This state-of-the-art mobile robot features legs that mimic human movements, enabling it to navigate various terrains such as stairs, rugged landscapes, and curved areas with ease. With its ability to inspect and scout hazardous environments, such as those involving chemicals and radioactivity, it has the potential to prevent dangerous accidents.

Quadruped robot solution for management and maintenace work in all facilities, power plants, chemical plants and any harmful or inferior environment

Customize the robot function based on modular design following any customer's request and easy maintenance

Provide the customizable solution attached with other equipment (thermal, monitor, noise, vibration, gas)

# **Specifications**

Index	Unit	Value
Length	mm	1,300
Width	mm	650
Weight	kg	50
Max speed	m/s	1.2
Battery capacity	Wh	1,440
Operating voltage	VDC	48
Operating time (typical)	Hours	2
Operating time (standby)	Hours	6
Payload (normal)	kg	10
Payload (maximum)	kg	20
Connectivity		802.11 Dual-band WiFi, LTE
Optional Equipment		Optical Camera, Thermal Camera, Mic



# AIDIN ROBOTICS

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