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## AIDIN

**ROBOTICS** Inc. is a robot company that <u>started from</u> <u>Robotics Innovation Laboratory in the Department of Mechan-</u> <u>ical Engineering at Sungkyunkwan University</u> in South Korea. Our expertise lies in developing robotic system and AI-driven sensor technologies based on our Field Sensing technology, which we have been accumulating since 1995.

The world's leading field sensing technology



# AIDIN ROBOTICS



### "

We are dedicated to the continuous pursuit of our vision: creating a safer working environment and coexistence between humans and robots.

"

## **One - stop Robotic Solution for Safe Collaboration**

Our focus is on preventing accidents and improving productivity between humans and industrial/collaborative robots.

## The Competitiveness of AIDIN ROBOTICS

The newest Power Sensing Technology which successfully overcomes the limitation of existing force/torgue sensing based on capacitance.



A manpower Unique Source Technology for focusing on researching robot field measuring capacitance 1/10 price Leading a domestic market compared to others for miniature, 6-axis sensor

## HISTORY

2019

Established corporation

#### 2020

Established Laboratory in company Selected as The beginning foundation support package program Selected as Tech Incubator Program for Startup Award of R-biz Challenge from Korea Association of Robot Industry Award of Korea Robot Company of The Year 2020 Award of Excellent Product in ROBOTWORLD 2020

#### 2021

Selected as Core-Tech Development Business in Robotics field (Task Scale 3 billion) Award of Korea Robot Company of The Year 2021 (Two years in a row) Award of Excellent Product in ROBOTWORLD 2021 (Two years in a row)

#### 2022

Attraction of investment Series A (4.5 billion Scale) Award of Korea Robot Company of The Year 2022 (Three years in a row) Award of Excellent Product in ROBOTWORLD 2022 (Three years in a row)

#### 2023

Selected as Deeptech Incubator for startup 1000+ Participate in ICRA 2023 exhibition Contract for developing quadruped robot with POSCO Award in International Robot Contest & R-biz Challenge 2023 Award of Korea Robot Company of The Year 2023 (Four years in a row) Award of Excellent Product in ROBOTWORLD 2023 (Four years in a row) Certification of Quality Management System ISO9001:2015

#### 2024

Selected as Cooperation Development Group of the evaluation focused on operating a skilled robot and supporting gripping performance (With Korea Electronics Technology Institute, National Institute of Standards and Technology) Contract for a local supply and sales with DINGS in China Attracted KRW 15 billion in Series B funding Signed an MOU with CJ Logistics for the development of robotic picking solution for logistics automation

Selected as the excellent company of robotics company foundation support program in Gyeong-gi do

- Certification of Venture Business & Technology with a limit under two billion
- Investment attraction from Future Play, Korea Development Bank Capital, Shinhan Bank capital

- Selected as Managing department developing the customized torque sensor for service robot
- MOU Contract for the extension of AI technology corporation for quadruped robot with Snuailab

## <sup>Business</sup> Area

#### Robot Sensor

Our self-developed Force/Torque sensor could be adapted at various industrial robots and grippers. It provides controlling force, measuring torque, and detecting collision. In addition, We help to gauge any distance and contact force with an innovated safety sensor.

#### Smart Gripper

It could be combined and utilized following a use environment and manufacturing places with a competitive feature of parallel gripping mode, high-accuracy and high-speed.

#### **Robotics Automation**

Our self-developed technology of gripper, Al vision Algorithm could spread Force control solution for Manufacturing automation applied for delivery process, welding, grinding etc, Robotic picking solution for logistics automation and Quadruped robot solution for inspecting industrial facilities.

## **PRODUCTS**

### Robot Sensor

#### Force/Torque Sensor





Smart 6 axis F/T Sensor AFT200-D80

Ultra-thin Joint Torque Sensor **ATSB-Series** 

#### F/T Sensor KIT



Smart 6-axis F/T Sensor KIT AFT200-KIT-RB

Smart 6-axis F/T Sensor KIT AFT200-KIT-NRMK

### Smart Gripper

End of Arm Tool



SusGrip SusGrip-FT

### <sup>•</sup>Robotics Automation System

**Robotic Solution** 



Force Control Solution for

Manufacturing Automation

Co-worker

\*Under Development



AiDIN



\*Released in 2025

**Robotic Picking Solution** 







Miniature 6 axis F/T Sensor AFT20-D15 AFT50-D15

#### Safety Sensor



Panoradar Sensor ARS-5000 \*Under Development

#### **Robot Hand**





#### Robot Controller



Industrial Facility Inspection Soulution \*Under Development



Real-time Robot Motion Controller ARC6

## Smart 6 axis F/T Sensor







Model AFT200-D80

#### Features

The advanced F/T sensor with high precision based on the fringe effect and capacitance

Essential sensor for robot wrists, enabling tool collision detection, tool weight compensation, force control, direct teaching tool, and object weight measurement

Excellent environmental resistance

4kV discharge test passed

IP56 obtained waterproof/dustproof rating



### Specifications

Index	Unit
Operating voltage	VDC
Max. safe excitation voltage	VDC
Nominal force range	Ν
Nominal torque range	Nm
Limit force (Fxyz)	Ν
Limit torque	Nm
Resolution (Fxyz)	Ν
Resolution (Txyz)	Nm
Maximum sample rate	Hz
Dimensions	mm
IP rating	
Operating temperature	

### Applications

- Industrial / Collaborative robot
- Lead-thru device
- Welding, sanding, grinding, assembly operations
- Warehouse robot
- Smart Factory / Automation

 KC Registration Number

 CAN
 R-R-And-AFT200-D8-C

 EtherNet
 R-R-And-AFT200-D8-EN

 EtherCAT
 R-R-Adn-AFT200-D8-EC



EtherCAT

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C (CAN)	EN (EtherNET)	EC (EtherCAT)
5	12	12
12	24	24
	200	
	15	
	300	
	25	
	0.15	
	0.015	
	1,000	
	D80 x H20.5	
IP56	IP65	IP65
	10-60 °C	

## Smart 6 axis **F/T Sensor KIT**

All-in-One F/T Sensor based on the advanced field sensing technology

Applicable Robot

- Rainbow Robotics RB3, RB5, RB10, RB16
- Neuromeka Indy7
- Accepting our partners



**Rainbow Robotics** 



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Model AFT200-KIT-RB AFT200-KIT-NRMK

#### Features

- F/T sensor applied with the self-developed
- technology with capacitance
- Support Plug&Play mode based on collaborative robot brand
- Provide Customized KIT for each collaborative robot band
- Easy Set-up mode in Teaching Pendant

#### Function

- Precise force measurement
- Force Control mode that any user could use directly in teaching pendant
- Collision detection and stop function through force measurement

### Specifications

Index	Unit	AFT200-KIT-RB C(CAN)	AFT200-KIT-NRMK C(CAN)
Weight	g	505 (Sensor 236g, Bracket 269g)	635 (Sensor 236g, Bracket 399g)
Operating voltage	VDC		5
Max. Safe excitation voltage	VDC		12
Nominal force range	Ν	200	
Nominal torque range	Nm	15	
Resolution(Fxyz)	Ν	0.15	
Resolution(Txyz)	Nm	0.015	
Dimensions	mm	D80 * H52.3	D80 * H56.3
IP Rating			IP56
Operating temperature		10-60°C	

#### Applications

Applicable to various processes requiring force control technology

(Polishing, Sanding, Grinding etc)

- Processes for assembling cables or components
- Industrial robot / Collaborative robot
- Smart Factory / Automation

## Ultra-thin Joint Torque Sensor





Dimensions

ATSB 50 : 84mm x 14mm ATSB 100 : 100mm x 16mm ATSB 200 : 100mm x 18mm ATSB 400 : 120mm x 20mm

**Applications Example** 

Collaborative Robot



#### Model ATSB 50 / 100 / 200 / 400

#### Features

Ultra-thin joint torque sensor for collaborative and articulated robots

Ultra-thin joint torque sensor accurately and sensitively measures torque applied to robot joints, enabling precise collision detection and torque control in a compact design.

Excellent environmental resistance 4kV discharge test passed **INCECE** 

### Specifications

Index	Unit	ATSB50	ATSB100	ATSB200	ATSB400
Operating voltage	VDC	5			
Max. safe excitation voltage	VDC		10		
Nominal torque range (T <sub>N</sub> )	Nm	50	100	200	400
Overload (related T <sub>N</sub> )	%	300			
Resolution	Nm	0.03	0.05	0.1	0.2
Weight	g	120	190	210	310
Dimensions	mm	D84 x H14	D100 x H16	D100 x H18	D120 x H20
Sample rate	Hz	1,000			
Temperature	10-60 °C				
Interfaces	CAN (2.0 A/B)				
Connector	4 PIN VCC / GND /CAN_H / CAN_L				

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- Collaborative robot
- Wearable robot
- Medical device
- Rehabilitation robot

## Miniature 6 axis F/T Sensor





Dimensions 15mm x 10.5mm

Application Examples Gripper



\* Example Image

Model AFT20-D15 AFT50-D15



The world's smallest 6-axis force/torque sensor

Suitable for mounting on the gripper's tip end to handle irregular objects such as food, rubber, and plastic injection-molded products without causing damage Applicable to VR, haptic devices, and medical fields as well

Excellent environmental resistance 4kV discharge test passed

KC Registration Number R-R-Adn-AFT20-D15

### Specifications

Index	Unit	AFT20-D15	AFT50-D15
Operating voltage	VDC		5
Max. safe excitation voltage	VDC		10
Force range	Ν	20	50
Torque range	Nm	0.1	0.25
Break force	Ν	30	75
Break torque	Nm	0.15	0.35
Force resolution	Ν	0.2	0.3
Torque resolution	Nm	0.0005	0.001
Sample rate	Hz	•	00
Dimensions	mm	D15	k H10.5
Weight	g	:	3.2
Temperature	10-50 °C		
Interfaces		CAN	
Connector	FPC: 0.5 pitch, 8pin Length: 50, 100, 200 mm For User: CAN_H / CAN_L / VCC / GND		

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### Applications

Gripper



VR / AR device



| Robot hand









| Medical device



## **Panoradar Sensor**

Safety sensor for detecting all people and objects set on a wrist of co-bot without any blind spot

\*Under Development



Model ARS-5000

#### Features

Safety sensor detecting an surrounding environment and any obstacles to make safe working environment for all workers

Obstacle Detection (Max 20m)

Providing a widen detecting scope and accuracy without any blind spot (Presence detection / Segmentation / Motion / Tracking / Speed detection)

Range Resolution: 3cm

■ 360 degree detection FoV

Digital output interface (EtherNet)

Obtaining safety zone

#### Specifications

Index	Value	Description
Measurement principle	FMCW – 60GHz	Ultra-wide bandwidth 5.8GHz
Sensing functions	Presence Detection / Segmentation / Motion / Tracking / Speed Detection	
Measurement	Direction, Proximity and Speed	
Angles	4x (±45°) Azimuth 4x (±45°) Elevation FoV	
Working range	Min: 10cm / Max: 20m	Flexible adjustment of aperture angle and distance
Range resolution	Up to 3cm	
Response time	120Hz	Up to 1KHz
Supply voltage	6 – 28Vcc	
Number of detection zones	6 x 4	
Interfaces	EtherNet	RJ45, PoE
Operating temperature	–20 °C +70 °C	
Environment	Harsh environment	Rain / Dust / EMI / Fog
Objects detection	Various objects	Glass, wood, paper, human, metallic objects
Dimensions	Diameter: 80mm, thickness: 20mm	
Sensor package	All in one	Sensor body + PoE Cable

- Industrial robot / Collaborative robot
- AMR / AGV
- Delivery robot
- Industrial robot for safety
- Quadruped robot
- Humanoid robot

## Smart Gripper SusGrip

Robot gripper providing many smart functions based on parallel motion



Susgrip-FT



**AFT-Mini** Minature 6 axis F/T Sensor



Susgrip



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Model SusGrip / SusGrip-FT

#### Features

- A widen parallel motion, High-precision (Max 128mm)
- Smart function (Object Detection, Automated Lock)
- Precise force control mode with force sensor
- (Susgrip-FT model)
- High-speed and Strong power with BLDC motor
- Safe use (No pinch point)

Intuitive GUI



KC Registration Number(SUSGRIP R-R-26a-SusGrip \*Only for SUSGRIP Model

### Specifications

Index
Gripping force
Stroke
Form-fit payload
Voltage
Max Current
Repetition accuracy
Position resolution
Speed
Weight

### Applications

Various manufacturing process (Pick & Place) / Sorting / Handling / Palletizing / Assembly / Measure

#### Industry

Semi-conductor / Service / Logistics / Healthcare / Retail



Unit	Value
Ν	90
mm	0-128
Kg	5
V	24
А	2
mm	0.1
mm	0.2
mm/s	60
gram	1215

## AIDIN HAND

## Human-sized Robot Hand





**5 X AFT-Mini** Miniature 6 axis F/T Sensor



#### Features

AIDIN ROBOTICS' proprietary humanoid hand featuring a 6-axis force/torque (F/T) sensor on the fingertip

Dexterous future-proof picking system: Capable of various grasping modes (power, 3-point, pinch, etc.) suitable for different types of objects, and featuring integrated 6-axis F/T sensors, it can reliably handle delicate objects without causing damage

Human-level compact size and light weight

Link-driven mechanism: Offers both high precision and high force efficiency

#### Specifications

Index	Unit
Grasping mode	Mode
Degree of Freedom (Finger)	DoF
Degree of Freedom (Hand)	DoF
Finger-tip force	Ν
Payload	kg
Size	mm
Weight	kg
Finger-tip sensor	EA

- Industrial / Collaborative robot
- Warehouse picking robot
- Home-service robot
- Prosthetic hand

Value		
Power Mode (cylindrical, spherical, etc.)		
Precision Mode (pinch, tripod, etc.)		
3		
15		
20 or 50		
15		
291 x 112 x 120		
1.3		
5		
(Miniature 6-axis F/T Sensor, AFT20-D15)		

## Real-time Robot Motion Controller

Rotones IIII ©



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Model ARC6

#### Features

Real-time motion/force controller for collaborative robots, designed to be compatible with AIDIN ROBOTICS' sensor products

Equipped with Xenomai, EtherCAT, and ROS middleware

#### Specifications

Index	Value	
CPU	6 <sup>th</sup> Generation Intel Core I Processor	
CPU TDP	i7-6600U	
Memory Type	DDR4 2133MHz	
Power	9 - 36 VDC	
Ethernet	Intel i210/i211, 10/100/1000Base-TX	
Connection	DP X1, DVI-I X 1, USB 3.0 X 4, USB 2.0 X 2,	
	COM ports (RS232, 422, 485)	
Operating Humidity	0 - 90 %	
Operating temperature	0 - 60 °C	
Interfaces	EtherNET, EtherCAT	
Operating System	RT-OS (Linux, Ubuntu, Xenomai)	

- Industrial / Collaborative robot
- Sanding, grinding, welding, assembly applications
- Articulated robot control
- Warehouse picking robot control

## **Solution**

\*Under developement

## Force Control Solution for Manufacturing Automation

Smart Force/Torque Sensor-Based No-Code Automation Solution

- Immediate task automation through intuitive robot teaching
- Applicable to various tasks such as grinding, polishing, welding, and more







2 X AFT200 Minature 6 axis F/T Sensor (AFT200)



SANDING







GRINDING







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Easy task teaching (points, trajectories, force, etc.)

Active surface force control technology through target force setting

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Adaptable to various objects, including flat/curved surfaces, narrow areas, and more

Attach a force torque sensor (AFT200) to the body to analyze the shape and stiffness of the surface to be processed, and perform polishing process with a constant

#### 2

Recognize the user's intentions on the robot handle and teach the robot to be easily controlled to the desired position by the user





# Solution



## **Robotic Picking Solution for Logistics**

<u>Effortless Object Recognition and Grasping</u>: Our cutting-edge logistics robot picking system is designed to recognize and grasp random objects without the need for any pre-registration process.

Integrated Al Vision Technology: We've developed our own Al vision algorithm, seamlessly integrated with a smart gripper capable of handling objects of various types and sizes. This integration allows our system to adapt to all objects found in logistics environments.

Optimized Object Handling: Through the unified control of both suction and the gripper, our system employs

suitable grasping strategies to effectively handle objects, ensuring a seamless and efficient logistics operation.

#### \*Released in 2025



#### Productivity

- Productivity : <u>950 pieces per hour</u>
- Weight of graspable objects : 5kg
- Size of graspable objects : 160mm

### System Dimensions



## **Picker controller**



#### Installation Requirements

- Power: 100-240V, 40-60Hz, 2200W
- Compressed Air : 4hp+ compressor recommended



Radius : 1.3m (Robot Arm : RB10)



## **Solution**



## Quadruped Robot for Industrial Facility Inspection Solution

\*Under Developent



### Applications

Inspecting Hazardous Facilities



| Monitoring Construction Sites



Smart city Security



| Military / Police / Firefighting



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| Thermal Inspection



Construction and BIM



#### Features

This state-of-the-art mobile robot features legs that mimic human movements, enabling it to navigate various terrains such as stairs, rugged landscapes, and curved areas with ease. With its ability to inspect and scout hazardous environments, such as those involving chemicals and radioactivity, it has the potential to prevent dangerous accidents.

Quadruped robot solution for management and maintenace work in all facilities, power plants, chemical plants and any harmful or inferior environment

Customize the robot function based on modular design following any customer's request and easy maintenance

Provide the customizable solution attached with other equipment (thermal, monitor, noise, vibration, gas)

### Specifications

Index	Unit	Value
Length	mm	1,300
Width	mm	650
Weight	kg	50
Max speed	m/s	1.2
Battery capacity	Wh	1,440
Operating voltage	VDC	48
Operating time (typical)	Hours	2
Operating time (standby)	Hours	6
Payload (normal)	kg	10
Payload (maximum)	kg	20
Connectivity		802.11 Dual-band WiFi, LTE
Optional Equipment		Optical Camera, Thermal Camera, Mic



# AIDIN ROBOTICS

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